Omid Taheri

Curriculum Vitae

PhD Candidate, MPI Tübingen, Germany
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③ Homepage
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"The best way to predict the future is to create it."

Education

Jul 2018 - Pres.	Max Planck Institute for Intelligent Systems, Tuebingen,	DE.
Degree	Ph.D. in Computer Science - Machine Learning and Computer Vision	
Supervisors	Prof. Michael J. Black, Dr. Dimitrios Tzionas	
2014 - 2017	Sharif University of Technology, Tehran,	, IR.
Degree	M.Sc. in Mechanical Engineering - Applied Mechanics (Control and Robotic)	
GPA	3.90/4 - Among top 2% students in the Department	
Thesis	Gait Tracking and Analysis Using IMU and RGB Camera Data Fusion Using EKF	
Supervisors	Prof. Aria Alasti, Prof. Hassan Salarieh	
2010 - 2014	Isfahan University of Technology, Isfahan,	, IR.
Degree	B.Sc. in Mechanical Engineering - Mechatronics	
GPA	3.97/4 - Ranked 1 st in the Mech. Eng. Department	
Thesis	Design of Spool-Sleeve Electrohydraulic Servo Salves Based on Desired Parameters	
Supervisor	Prof. Saeed Behbahani	
	Publications	
1	GRIP: Generating Interaction Poses Conditioned on Object and Body Motion (Under Submiss	ion)
CVPR - 2023	O Taheri , Yi Zhou, D Tzionas, Ya Zhou, D Ceylan, S Pirk, MJ Black	
	Paper — Project Website — Github Code	
2	ARCTIC: Articulated Objects in Free-form Hand Interaction (Under Submission)	
CVPR - 2023	Z Fan, O Taheri , D Tzionas, M Kocabas, M Kaufmann, MJ Black, O Hilliges	
	Paper — Project Website	
3	IPMAN: 3D Human Pose Estimation via Intuitive Physics (Under Submission)	
CVPR - 2023	S Tripathi, L Müller, C Huang, O Taheri , MJ Black, D Tzionas	
4	GOAL: Generating 4D Whole-Body Motion for Hand-Object Grasping	
CVPR - 2022	O Taheri , V Choutas, MJ Black, D Tzionas	
	Paper — Project Website — Github Code	
5	InterCap: Joint Markerless 3D Tracking of Humans and Objects in Interaction	
GCPR - 2022	Y Huang, O Taheri , MJ Black, D Tzionas	
	Paper — Project Website — Github Code	

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6	GRAB: A Dataset of Whole-Body Human Grasping of Objects				
ECCV - 2020					
	Paper — Project Website — Github Code				
7 arXiv - 2017	Human Leg Motion Tracking by Fusing IMUs and RGB Camera Data Using EKF O Taheri, H Salarieh, A Alasti Paper				
	Research Interests				
	o Virtual Avatar Animation o Human-Object Interaction	ı			
	o Grasp Prediction o Motion Synthesis and Tra				
	o Object-Interaction Detection o 3D Geometry Representat	ion			
	Experience				
	Research & Work				
Jun-Nov 2022	PhD Research Intern, Adobe Inc.,	Remote, San Jose.			
July 2022	ICVSS Summer School, Winner of the AWS reading-group challenge.	Sicily, IT.			
July 2021	PAISS Summer School,	Grenoble, Remote.			
2018 - Present	Motion Capture , <i>Max Planck Institute for Intelligent Systems</i> , Collecting motion data with various systems including:	Tuebingen, DE.			
	 Vicon MoCap System 3D Scanners IMU Sensors Gaze Transition 				
2016 - 2017	Motion Analysis Researcher, <i>Movafaghian Research Center</i> , Capturing and analyzing human motion data using IMU sensors and R	Tehran, IR. GB cameras.			
2015 - 2016	Control Engineer, Rahpooyane Aflak Corporation,Tehran, IfHead of the control team in a project for tele-driving of manual carsTehran, If				
2014 - 2015	Startup , <i>Self-Employement</i> , Design and Fabrication of a Controller Board for AC to DC Conversion				
Jun-Sep 2014	Summer Internship , <i>Kian-Control Corporation</i> , Isfahan, IR Worked on automation of a company production line using Siemens PLCs				
	Teaching				
Jan-Jun 2015	Teaching Assistant, B.Sc., Sharif University of Technology,	Tehran, IR.			
	• Mechanics of Materials and Statics • Dynamic and Control L	aboratory			
Jan-Jun 2014	Teaching Assistant, B.Sc. , <i>Isfahan University of Technology</i> , Mechatronics Laboratory	lsfahan, IR.			
	Awards & Honors				
2023	Selected as Finalist, Meta PhD Fellowship Program,	Meta Inc.			
2022	Winner of the AWS reading group competition, ICVSS Summer School,	Sicily, IT.			
2021	Admitted to IMPRS-IS Program, MPI for Intelligent Systems,	Tuebingen, DE.			

- 2018 Ph.D. Fellowship, Max Planck Institute for Intelligent Systems, Tuebingen, DE. 2018 Ph.D. Fellowship (Declined), Sharif University of Technology, Tehran, IR. Tehran, IR.
- 2014 2018 Member of Iran's National Elites Foundation,

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2010 - 2017 Recognized as Exceptionally-Talented Student, Tehran, IR. 2014 Honary M.Sc. Admission, Sharif University of Technology, Tehran, IR. 2014 M.Sc. Fellowship (Declined), Amirkabir & Isfahan Uni of Technology, Tehran, IR. 2013 & 2014 Ranked 4th & 6th in National Olympiad of Mech. Eng., Tehran, IR. 2010 - 2014 Ranked 1st in Mechanical Engineering Department in B.Sc., Isfahan, IR. 2010 Among Top 0.5% in National University Entrance Exam, Isfahan, IR.

Skills

-Team Management

- 2019 2021 **Data Capturing and Data Cleaning Team**, *MPI for Intelligent Systems*, Tuebingen, DE. Managing a team of three persons working on capturing and cleaning motion data.
- 2015 2016 **Control Engineering Team**, *Rahpooyane Aflak Corporation*, Tehran, IR. Managing a team of three students working on control and tele-drive of manual cars.

-Mentoring

2022 Farzaneh Seyedshahi, Co-Supervised, MPI for Intelligent Systems, Tuebingen, DE.

-Tools & Topics

Python	MATLAB	C & C++	PyTorch
TensorFlow	Motion Capture	Blender	Autodesk Inventor
Deep Learning	Machine Learning	3D Geometry	

Talks & Presentations

- 2022 GOAL: Generating 4D Whole-Body Motion for Hand-Object Grasping (Poster), @CVPR.
- 2021 Training Avatars How to Grasp 3D Objects (Poster), @PAISS Summer School.
- 2021 Training Virtual Humans How to Interact With Objects (Lightning Talk),
Honorable mention prize as a top 5% talk,@IMPRS Bootcamp Tuebingen, DE.
- 2020 GRAB: A Dataset of Whole-Body Human Grasping of Objects (Talk & Poster), @ECCV - Online.
- 2020 GRAB: A Dataset of Whole-Body Human Grasping of Objects (Talk),
- 2019 Accurate Hand Tracking using IMU sensors (Talk), @MPI_IS Tuebingen, DE. @MPI_IS - Tuebingen, DE.
- 2017 Gait Tracking and Analysis Using IMU and RGB Camera Data Fusion Using EKF (Talk), @SUT - Tehran, IR.

Community Service Paper Review 2022 • CVPR (2 Papers) • IJCV (1 Paper) 2021 • 3DV (3 Papers) • TPAMI (1 Paper) • ICCV (3 Papers) 2020 • CVPR (1 Paper) • ECCV (1 Paper)